

CD AUTO CHANGER

KDC-C510FM

SERVICE MANUAL

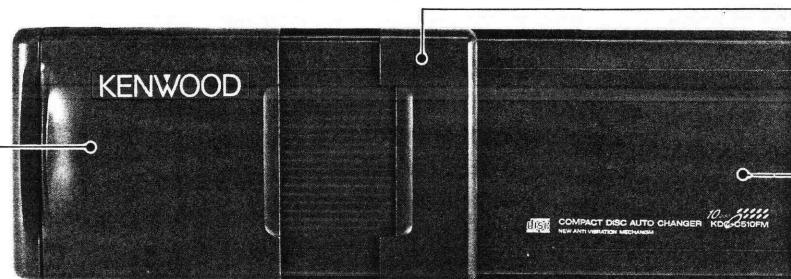
KENWOOD

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B51-7292-00(MC) 3296

When transporting this model, always attach CAUTION CARD and STEPPED SCREW (for transportation).
CAUTION CARD : B58-1275-04
STEPPED SCREW: N09-4186-25

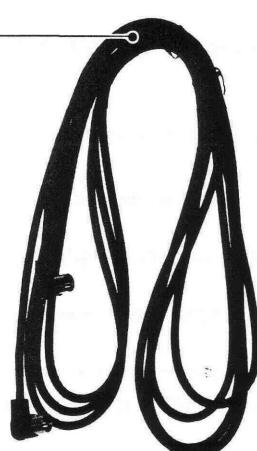
| Service jig | Parts No. |
|------------------------------|-------------|
| For initial position setting | W05-0635-00 |

Dressing panel
(A21-2395-02):Gray
(A21-2390-02):Black



Dressing panel
(A21-2353-42):Gray
(A21-2392-02):Black

Cord with plug
(E30-4138-05)

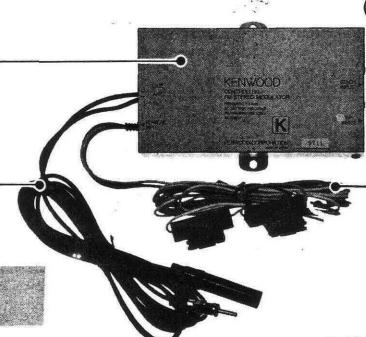


Holder assy (Magazine)
(J19-4676-42)

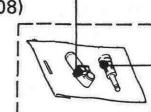
*M type only
Mounting hardware assy
(J21-7775-04)

DC cord
(E30-4473-08)

Case
(A01-2642-08)



Antenna cord assy
(E30-4310-08)

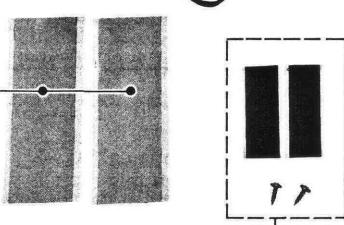


Holder assy
(B07-2138-08)

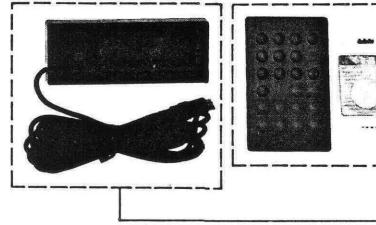
Blind plate
(F19-1303-04)

For K • E type
Screw set
(N99-1645-15)

*M type only
Adhesive tape
(J69-0506-04)



Magtape assy
(W01-0763-08)



Remote controller assy
(A70-0864-05)

Display unit assy
(T95-0241-08)

The MECHANISM OPERATION DESCRIPTION is the same as model KDC-C710.
Please refer to the service manual of model KDC-C710 (B51-7104-00).

MICROCOMPUTER'S DESCRIPTION

TEST Modes E-88 test mode

●How to enter

While holding the magazine eject SW, reset the unit and keep on holding the eject SW for more second to enter the E-88 mode.

(Note) In the E-88 mode, the initial position detection operation at the time of reset start is not performed.

●Manual operation functions

The E-88 display appears when the H/U is set to the changer mode.

In this condition, the changer mechanism can be operated manually using the track search up/down and disc search up/down keys.

- | | |
|------------------------|---|
| Track search Up key: | Operates the spindle/loading motor in the direction for pulling the disc tray into the mechanism deck (disc loading direction). |
| Track search Down key: | Operates the spindle/loading motor in the direction for returning the disc tray into the magazine (disc ejection direction). |
| Disc search Up key: | Operates the ELV motor in the direction for moving the mechanism deck upward. |
| Disc search Down key: | Operates the ELV motor in the direction for moving the mechanism deck downward. |

●Position adjustment function

This function writes the mechanism position adjustment values in the EEPROM in the E-88 mode.

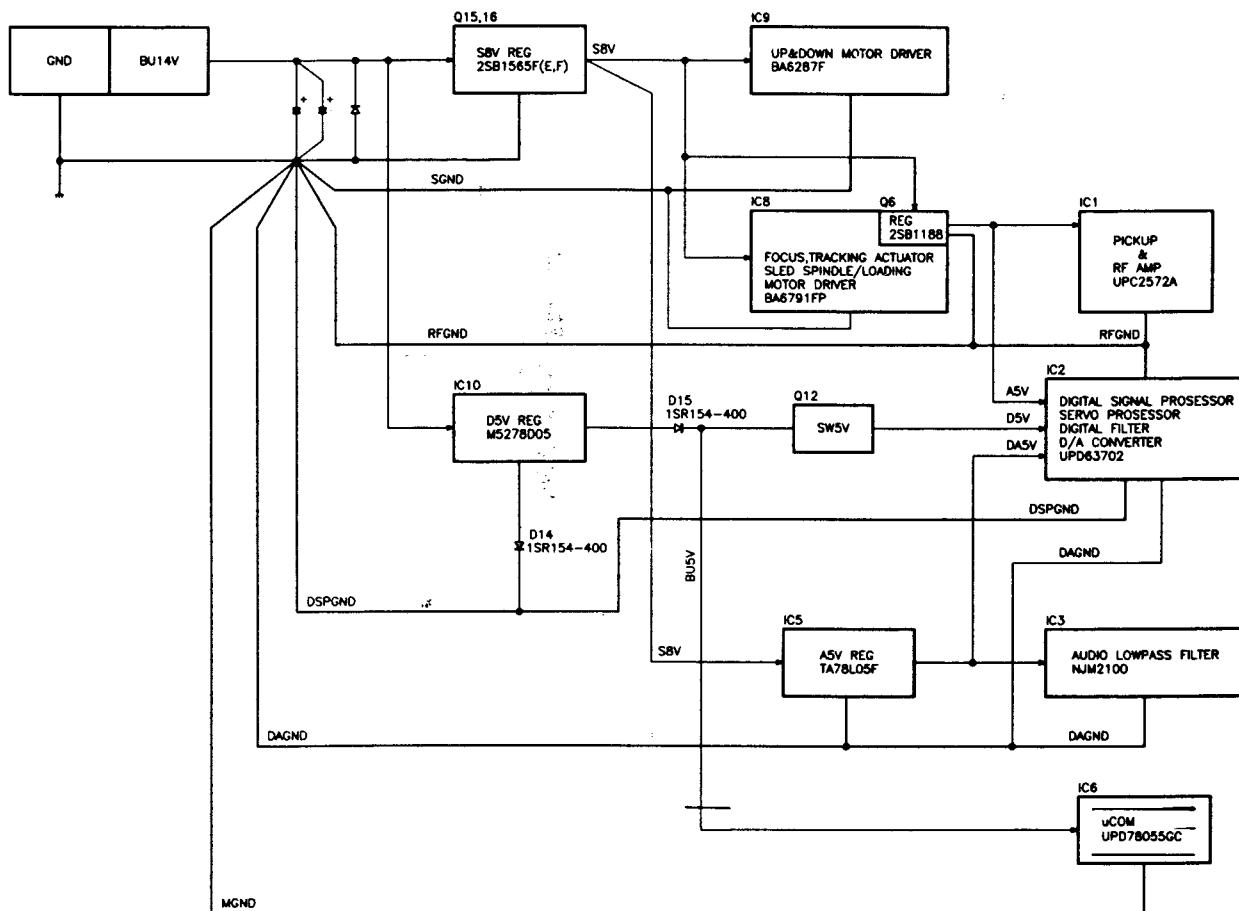
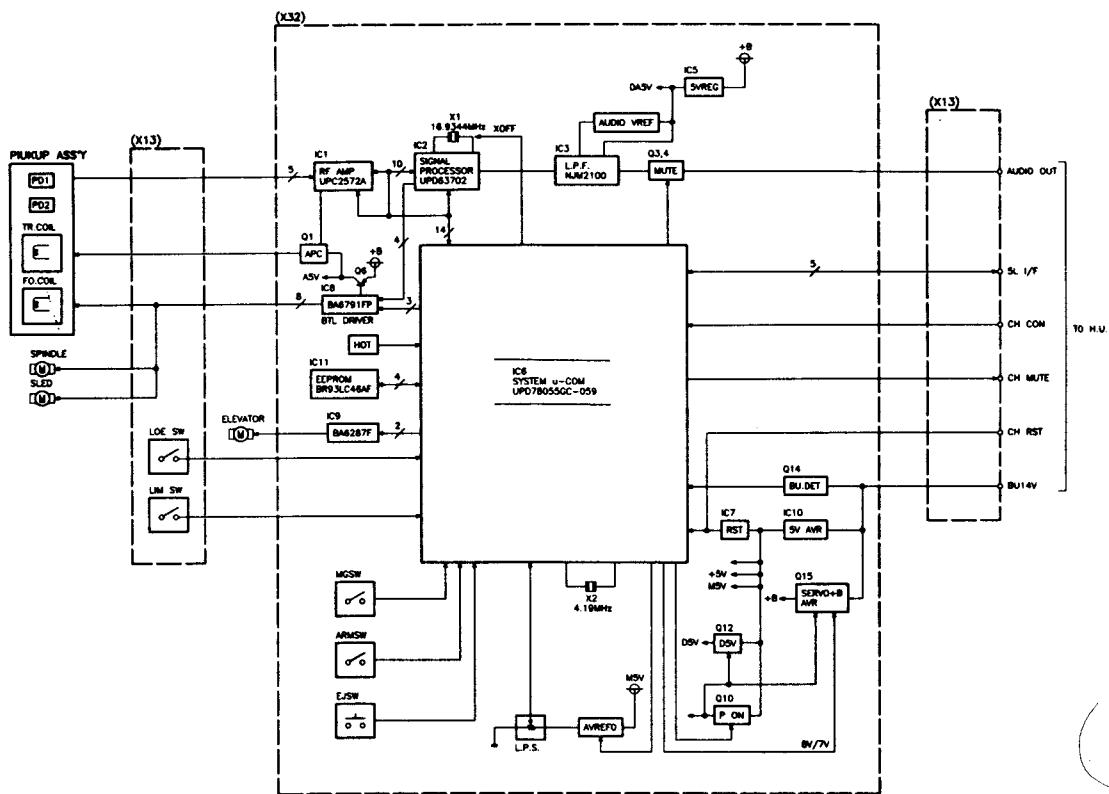
Adjustment procedure

1. With the mechanism in the magazine ejection condition, move the mechanism manually up and down to set the mechanism to the reference position.
2. Pressing the REP key of the H/U starts the judgment of the mechanism position and the distinction whether the changer is a 6-disc or 10-disc changer.
If the mechanism position is extremely deviated from the reference position, the processing is aborted immediately.
3. The offset from the reference position is calculated and the 6/10 data and offset values are written in the EEPROM.
4. Data is read from the EEPROM to judge whether it has been written normally.
When it is judged that the write operation has completed normally, the mechanism deck moves to the magazine ejection standby position.
When it is judged that the write operation was abnormal, the mechanism performs no operation.

(Note) Mechanism reference position

- 6-disc mechanism: Position of the 3rd stage
10-disc mechanism: Position of the 6th stage

BLOCK DIAGRAM



COMPONENTS DESCRIPTION

CD PLAYER UNIT(X32-4260-01)

| Ref.No. | Prts No. | Use and Function | Operation and condition |
|---------|----------------|---|--|
| IC1 | UPC2572A | RF amp & error amp | RF amplifier, focusing/tracking error amplifier, APC circuit, reference amplifier, mirror circuit, defect circuit, RF OK circuit, EFM comparator and vibration detector circuit. |
| IC2 | UPD63702A | Digital servo data processor | Digital servo data processor, 8fs oversampling filter, D/A converter, digital loop filter. |
| IC3 | NJM2100M | D/A converter output active filter | Differential amplifier. |
| IC5 | TA78L05F | 3-pin regulator | Supplies 5 V to the D/A converter and active filter. |
| IC6 | UPD78055GCA25T | System u-COM | |
| IC7 | PST9137NR | Reset IC | |
| IC8 | BA6791FP | Motor drive | Drives the focusing/tracking actuators, sled motor and spindle motor. |
| IC9 | BA6417F | Motor drive | Drives the mechanism deck up-down motor. |
| IC10 | M5278D05 | 3-pin regulator | 5 V power supply for the servo circuitry. |
| IC11 | AK93C45AF | Memory IC | Storage of data on the initial position of the mechanism deck up-down operation and on the distinction between 10-disc and 6-disc changer. |
| Q1 | 2SA1362(Y) | Laser control | Controls the laser current according to the voltage output from the IC1 LD terminal. |
| Q2 | DTC124EK | Clock ON/OFF | Clock is turned OFF when the IC6 XOFF terminal outputs "H". |
| Q3,Q4 | 2SD2114K | Audio muting | Muting is turned ON when IC6 A.MUTE outputs "L". |
| Q5 | DTA124EK | Audio muting | Muting is turned ON when IC6 A.MUTE outputs "L". |
| Q6 | 2SB1188 | 5 V optics power | Supplies the power from AVR 8 V to the A.VDD of the P-U, IC1 and IC2. |
| Q7 | DTC124EK | H/U communication control | Inverts the CH-CON logic. |
| Q8 | DTC124EK | Reset SW | The microcomputer is reset when CH-RST goes "H". |
| Q9 | DTA114EK | LPS power SW | Goes ON when LPSCO of IC6 goes "L" at P-ON or during up-down operation. |
| Q10 | 2SA1362(Y) | P-ON SW | |
| Q11 | DTA143EK | H/U communication control | Inverts the CH-MUTE logic. |
| Q12 | 2SA1362(Y) | Servo 5 V drive | |
| Q13 | DTC124EK | Servo 5 V SW | Goes ON/OFF at P-ON. |
| Q14 | DTC124EK | B-U power detect SW | |
| Q15 | 2SB1655(E,F) | 8 V AVR drive | |
| Q16 | 2SC2412K | 8 V AVR drive | |
| Q17 | DTA143EK | 8 V AVR SW | Turned ON/OFF by P-ON. |
| Q18 | DTC124EK | 8 V AVR SW | Turned ON/OFF by P-ON. |
| Q19 | DTC124EK | AVR 8 V/7 V SW | 7 V when "H" (normal play mode).8 V when "L" (mechanism loading-ejection operation, ELV). |
| Q20,Q21 | DTC114YK | Focusing/tracking hold upon scratch detection | When a scratch is detected, holds the focusing error and tracking error signals at the reference. |
| Q22 | 2SC2412K | Scratch detect SW | |

MICROCOMPUTER'S DESCRIPTION

System µ-com:UPD7805GC (X32-4260-01:IC6)

Terminal description

| Pin No. | Pin Name | I/O | Name | Pin Type | Function |
|---------|----------|-----|--------|-----------------|--|
| 1 | P15 | I | EDI | Push-pull | EEPROM data input. |
| 2 | P16 | O | EDO | Buffer | EEPROM data output. |
| 3 | P17 | O | ECLK | Buffer | EEPROM clock output. |
| 4 | AVss | | AVss | | |
| 5 | P130 | O | ECS | Push-pull | EEPROM chip select output. |
| 6 | P131 | O | REQC | Push-pull | Changer request output for 5-wire communication. |
| 7 | AVref1 | | AVref1 | | D/A converter reference voltage input |
| 8 | P70 | I | SDI | Push-pull | Data input from servo IC. |
| 9 | P71 | O | SDO | Buffer | Data output to servo IC. |
| 10 | P72 | O | SCK | Push-pull | Clock output to servo IC. |
| 11 | P20 | O | | Push-pull | Not used (open). |
| 12 | P21 | O | | Push-pull | Not used (open). |
| 13 | P22 | O | | Push-pull | Not used (open). |
| 14 | P23 | O | DGCON | Push-pull | Digital output control (not used) |
| 15 | P24 | O | AMUTE | Push-pull | Audio muting output. |
| 16 | P25 | I | DATAH | Schmitt trigger | H/U data input for 5-wire communication. |
| 17 | P26 | O | DATAC | Push-pull | Changer data output for 5-wire communication. |
| 18 | P27 | O | CHCLK | Push-pull | Changer clock output for 5-wire communication. |
| 19 | P40 | O | CHSEL | Push-pull | Changer 1/2 switching. |
| 20 | P41 | O | TSTB | Push-pull | Test mode strobe output. |
| 21 | P42 | O | TCLK | Push-pull | Test mode clock output. |
| 22 | P43 | O | TDATA | Push-pull | Test mode data output. |
| 23 | P44 | O | 8/7V | Push-pull | |
| 24 | P45 | O | | Push-pull | Not used. |
| 25 | P46 | O | | Push-pull | Not used. |
| 26 | P47 | O | | Push-pull | Not used. |
| 27 | P50 | I | ARM_SW | Buffer | Arm SW input. |
| 28 | P51 | O | TM4 | Push-pull | 4x-speed mode control output (not used). |
| 29 | P52 | O | TM2 | Push-pull | 2x-speed mode control output (not used). |
| 30 | P53 | O | XOFF | Push-pull | Servo IC oscillation OFF control output. |
| 31 | P54 | O | CHCONO | Push-pull | CHCON output to stack changer. |
| 32 | P55 | O | STB | Push-pull | Strobe output to servo IC. |
| 33 | Vss | | Vss | | Ground potential. |
| 34 | P56 | O | A0 | Push-pull | A0 output to servo IC. |
| 35 | P57 | O | RST | Push-pull | Reset output to servo IC. |
| 36 | P60 | I | ADJSEL | Buffer | Servo automatic adjustment invalidation selection terminal (for use in testing). |
| 37 | P61 | I | LOCK | Buffer | Spindle servo lock detection. |
| 38 | P62 | I | RFOK | Buffer | RF OK. |
| 39 | P63 | I | TBCI | Buffer | Tracking filter bank switching input. |
| 40 | P64 | O | TBCO | Push-pull | Tracking filter bank switching output. |
| 41 | P65 | O | LAON | Push-pull | Laser ON. |
| 42 | P66 | I | LIMSW | Push-pull | Limit switch input. |
| 43 | P67 | I | 8/12SW | Push-pull | 8 cm/12 cm judgment switch (not used). |

MICROCOMPUTER'S DESCRIPTION

Terminal description

| Pin No. | Pin Name | I/O | Name | Pin Type | Function |
|---------|----------|-----|---------|-----------------|--|
| 44 | P30 | I | LEDSW | Push-pull | Loading end switch input. |
| 45 | P31 | O | SP/LO+ | Push-pull | Spindle/loading motor output +. |
| 46 | P32 | O | SP/LO- | Push-pull | Spindle/loading motor output -. |
| 47 | P33 | O | DMUTE | Push-pull | Driver muting. |
| 48 | P34 | O | ELV+ | Push-pull | Up-down motor output +. |
| 49 | P35 | O | ELV- | Push-pull | Up-down motor output -. |
| 50 | P36 | O | CH_MUTE | Push-pull | Changer muting output. |
| 51 | P37 | O | PON | Push-pull | P-ON output. |
| 52 | P120 | I | TYPE0 | Buffer | Test mode input 0. |
| 53 | P121 | I | TYPE1 | Buffer | Test mode input 1. |
| 54 | P122 | I | TYPE2 | Buffer | Test mode input 2. |
| 55 | P123 | I | TYPE3 | Buffer | Test mode input 3. |
| 56 | P124 | O | SLNSA | Push-pull | Sled dead sector invalidation setting (for testing). |
| 57 | P125 | I | COMSEL1 | Buffer | u-COM destination type terminal 1. |
| 58 | P126 | I | COMSEL2 | Buffer | u-COM destination type terminal 2. |
| 59 | P127 | I | ELVADJ | Buffer | Up-down position adjustment mode terminal. |
| 60 | RESET | | RESET | | |
| 61 | P00 | I | SBSY | Schmitt trigger | Subcode Q input timing detection input. |
| 62 | P01 | I | MGSW | Schmitt trigger | Magazine switch input. |
| 63 | P02 | I | EJSW | Schmitt trigger | Eject switch input. |
| 64 | P03 | I | REQH | Push-pull | REQH input. |
| 65 | P04 | I | REQC2 | Push-pull | CH2 REQC input. |
| 66 | P05 | I | CH_CON1 | Push-pull | CH1 control input from H/U. |
| 67 | P06 | I | BU_DET | Push-pull | B-U detection. |
| 68 | Vdd | | Vdd | | Positive power supply. |
| 69 | X2 | | X2 | | Main clock (4.19 MHz) connection terminal 2. |
| 70 | X1 | | X1 | | Main clock (4.19 MHz) connection terminal 1. |
| 71 | IC | | IC | | Internally connected. |
| 72 | XT2 | | XT2 | | |
| 73 | XT1 | I | CH_CON2 | | CH2 control input from H/U. (Stack changer) |
| 74 | AVdd | | AVdd | | Analog power supply of A/D converter. |
| 75 | AVref0 | | AVref0 | | Reference input voltage of A/D converter. |
| 76 | P10 | I | KEY | A/D converter | Key input terminal (for test mode). |
| 77 | P11 | I | HOT | A/D converter | High temperature detection terminal. |
| 78 | P12 | I | LPS | A/D converter | Linear position sensor. |
| 79 | P13 | O | | A/D converter | |
| 80 | P14 | O | LPSCO | A/D converterL | PS power control. |

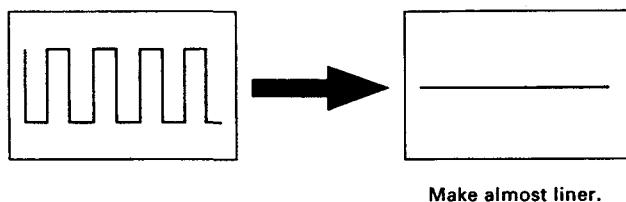
KDC-C510FM

ADJUSTMENT

• RF MODULATOR UNIT

1.DC balance adjustment (VR301)

While observing the waveform with a oscilloscope at pin 13 of IC301, adjust VR301 to minimize the waveform level.



• POSITION ADJUSTMENT

1.LPS initial position adjustment procedure

Connect the changer to the H/U. While holding the magazine [EJECT] key of the changer, press the [RESET] key of the H/U and, in about 1 second, release the magazine [EJECT] key. Press the [CD] key of the H/U to enter the E-88 mode. Move the mechanism deck to around the 1st stage by pressing the [DISC-] or [DISC+] key.

Insert the adjustment tool into the tool hole on the changer mechanism. Then press the [DISC+] key to move the mechanism deck until the mechanism's slider hits the adjustment tool. When the motor locks (stops) press the [REPEAT] key of the H/U.

When the [REPEAT] key is pressed, the mechanism moves automatically to the 1st stage and the initial position adjustment completes. (The data is written in the EEPROM at this time)

2.PLL control voltage adjustment (VR301)

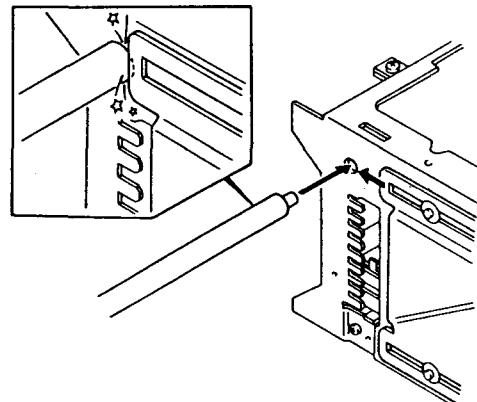
First set the transmission frequency to *87.9 MHz with the commander, then adjust VC301 so that the DC Voltage at the + pole of C317, measured using a multimeter or digital tester, is + 3V (± 0.1 V).

*NOTE:E type is 87.7MHz

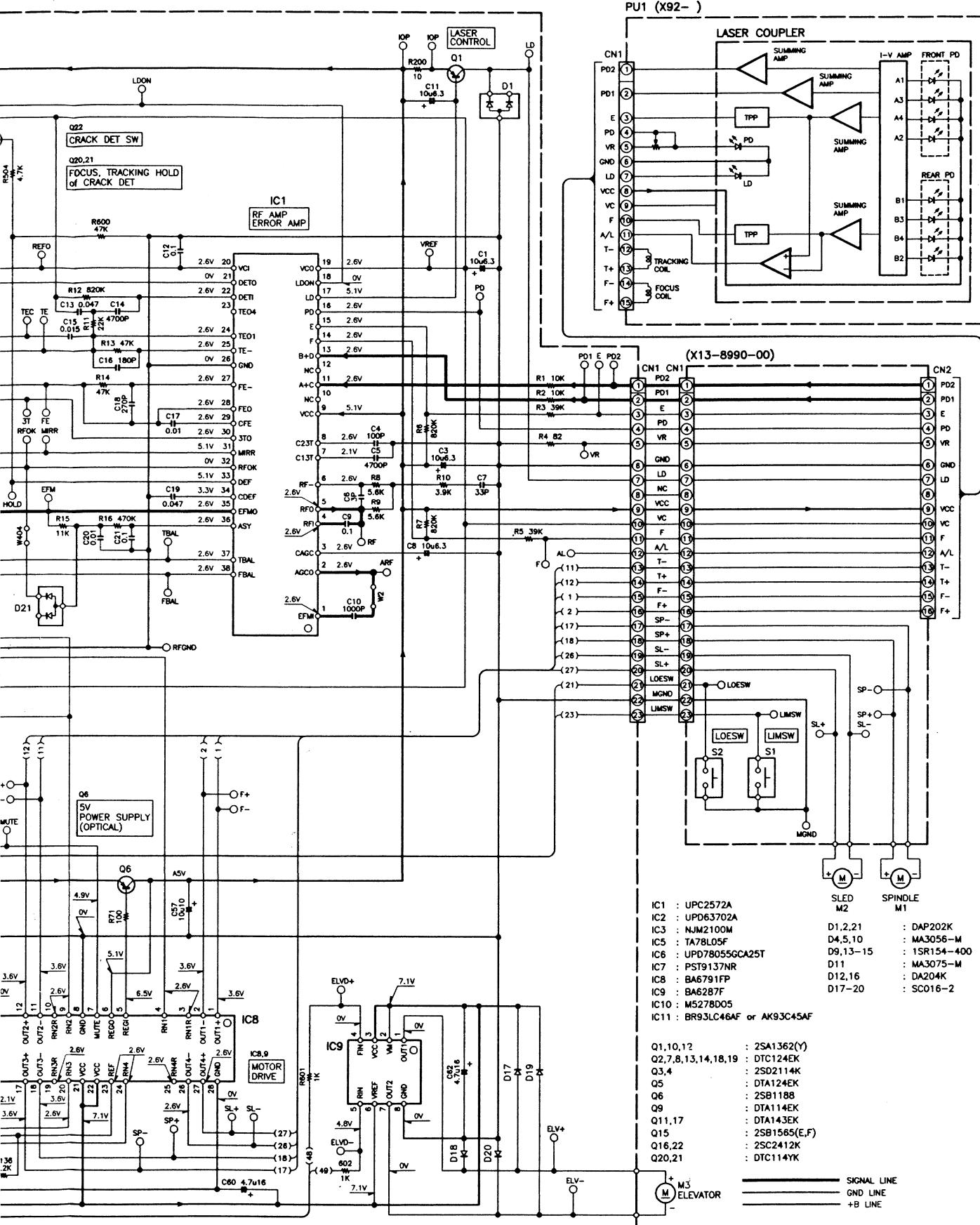
3.Modulation level adjustment (VR303)

The method using a standard receiver or tuner.

Adjust VR303 so that the output level from the standard receiver or tuner is as specified. The positions of the VRs and switches should be set prior to this adjustment.



ADJUSTMENT TOOL : W05-0635-00



IC1 : UPC2572A
 IC2 : UPD63702A
 IC3 : NJM2100M
 IC5 : TA78L05F
 IC6 : UPD78055GCA25T
 IC7 : PST9137NR
 IC8 : BA6791FP
 IC9 : BA6287F
 IC10 : MS278005
 IC11 : BR93LC46AF or AK93C45AF

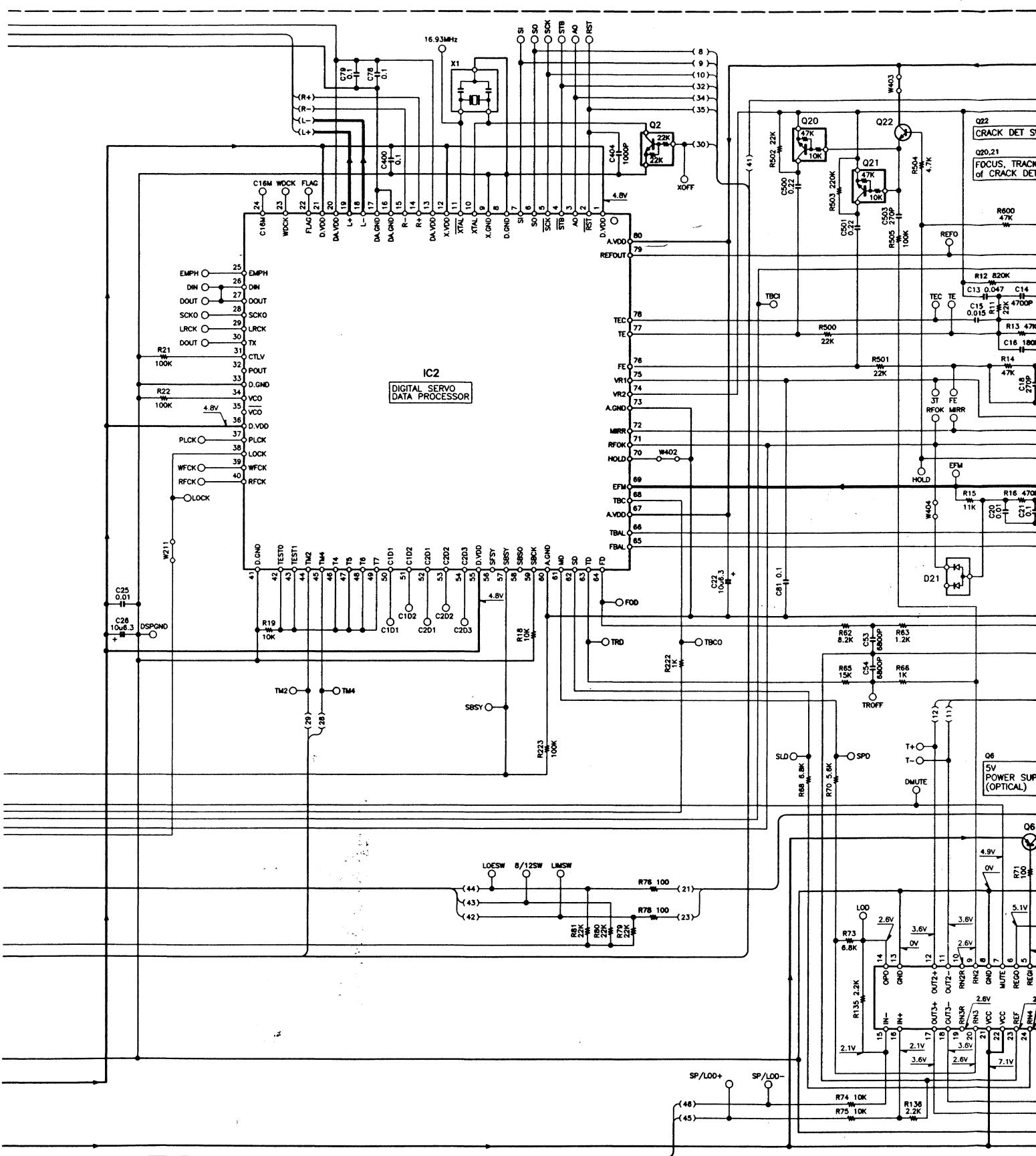
D1,2,21 : DAP202K
 D4,5,10 : MA3056-M
 D9,13-15 : 1SR154-400
 D11 : MA3075-M
 D12,16 : DA204K
 D17-20 : SC016-2

Q1,10,12 : 2SA1362(Y)
 Q2,7,8,13,14,18,19 : DTC124EK
 Q3,4 : 2SD2114K
 Q5 : DTA124EK
 Q6 : 2SB1188
 Q9 : DTA114EK
 Q11,17 : DTA143EK
 Q15 : 2SB1565(E,F)
 Q16,22 : 2SC2412K
 Q20,21 : DTC114YK

SIGNAL LINE
 GND LINE
 +B LINE

and rating fuse(s). To reduce the risk of electric shock, leakage-current or resistance measurements shall be carried out (exposed parts are acceptably insulated from the supply circuit) before the appliance is returned to the customer.
 (refer to
 or contin-
 uous type)

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DC voltages are as measured with a high impedance voltmeter. Values may vary slightly due to variations between individual instruments or/and units.

CAUTION : For continued safety, replace safety critical components only with manufacturer's recommended parts (refer to parts list). Δ indicates safety critical components. For continued protection against risk of fire, replace only with same type and rat current posed before

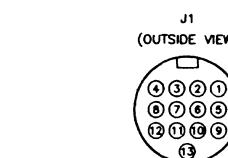
K

L

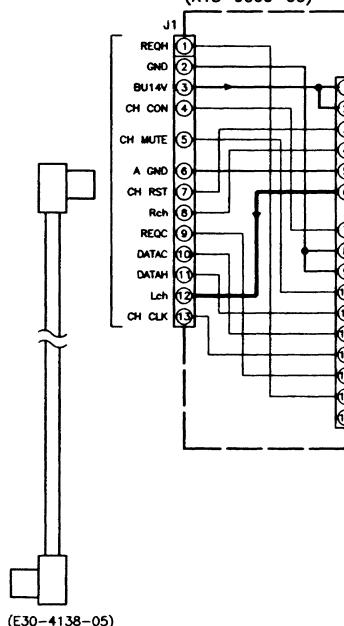
M

N

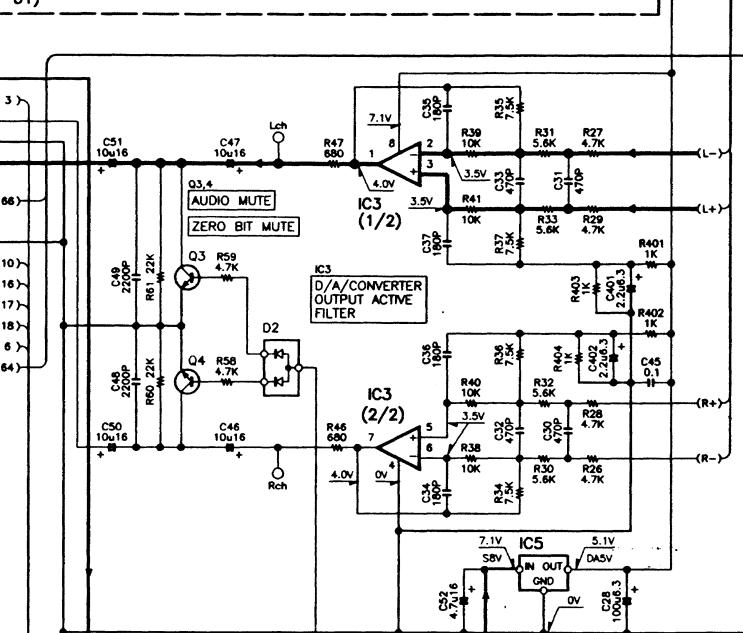
O



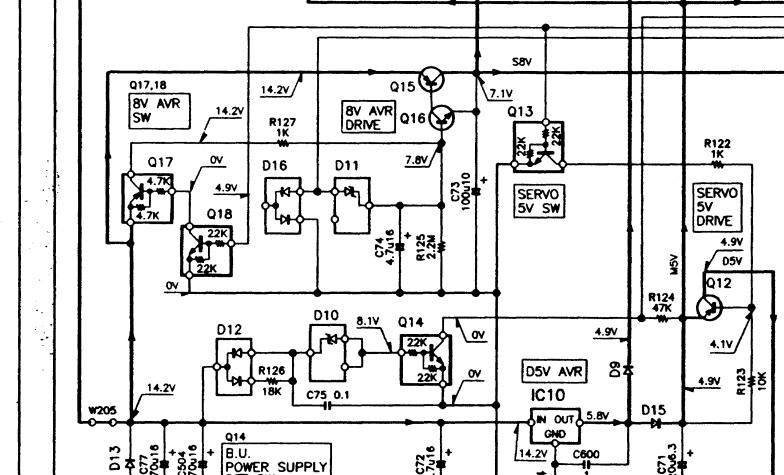
(X13-9000-00)



(X32-4260-01)



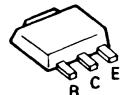
(E30-4138-05)



DTA114EK
DTA124EK
DTA143EK
DTC124EK
2SA1362
2SC2412K
2SD2114K



2SB1188



TA78L05F



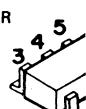
DA204K

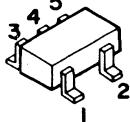
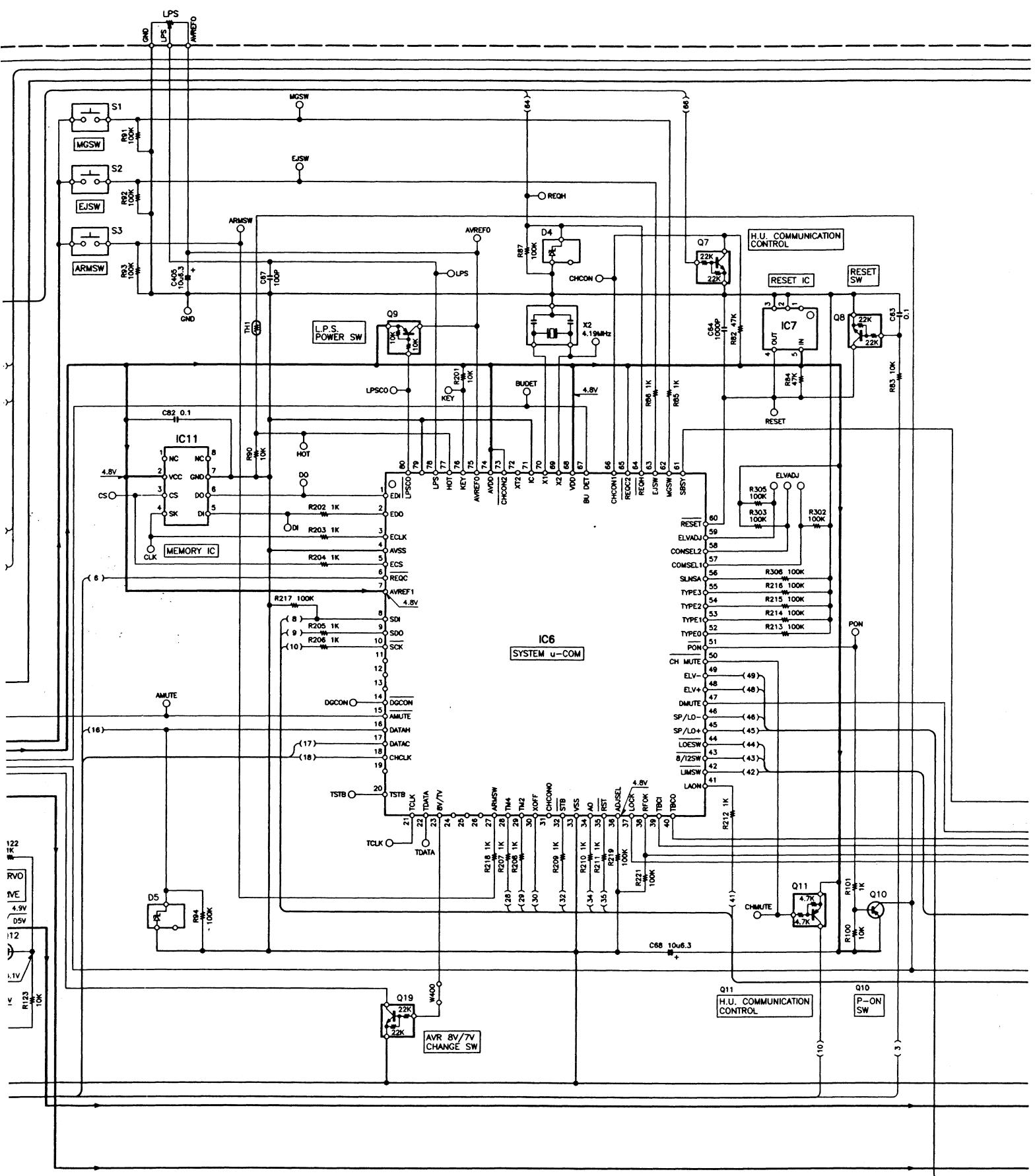


M5278D05

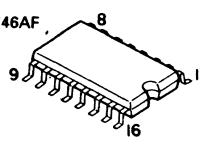


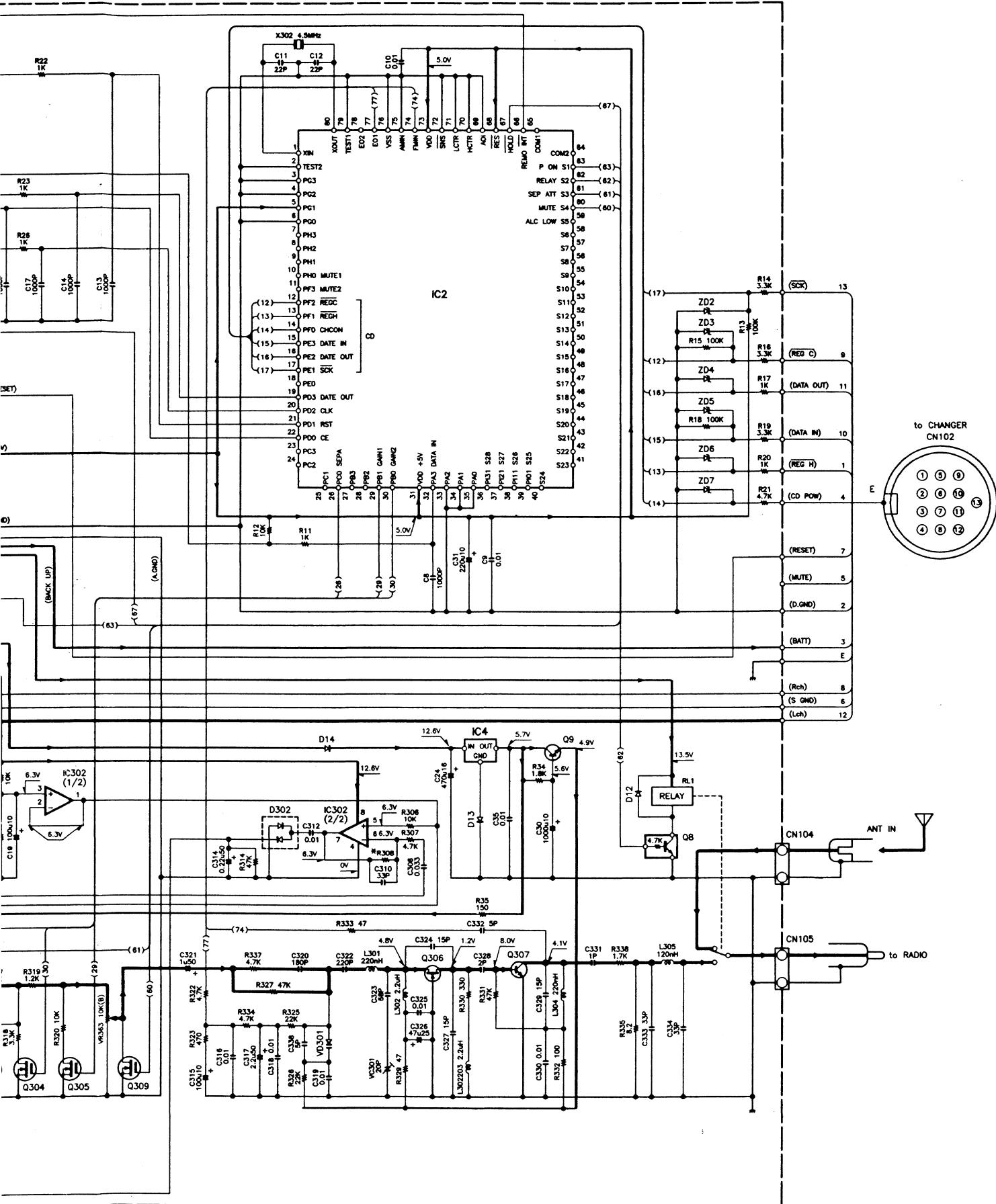
PST9137NR





BR93LC46AF



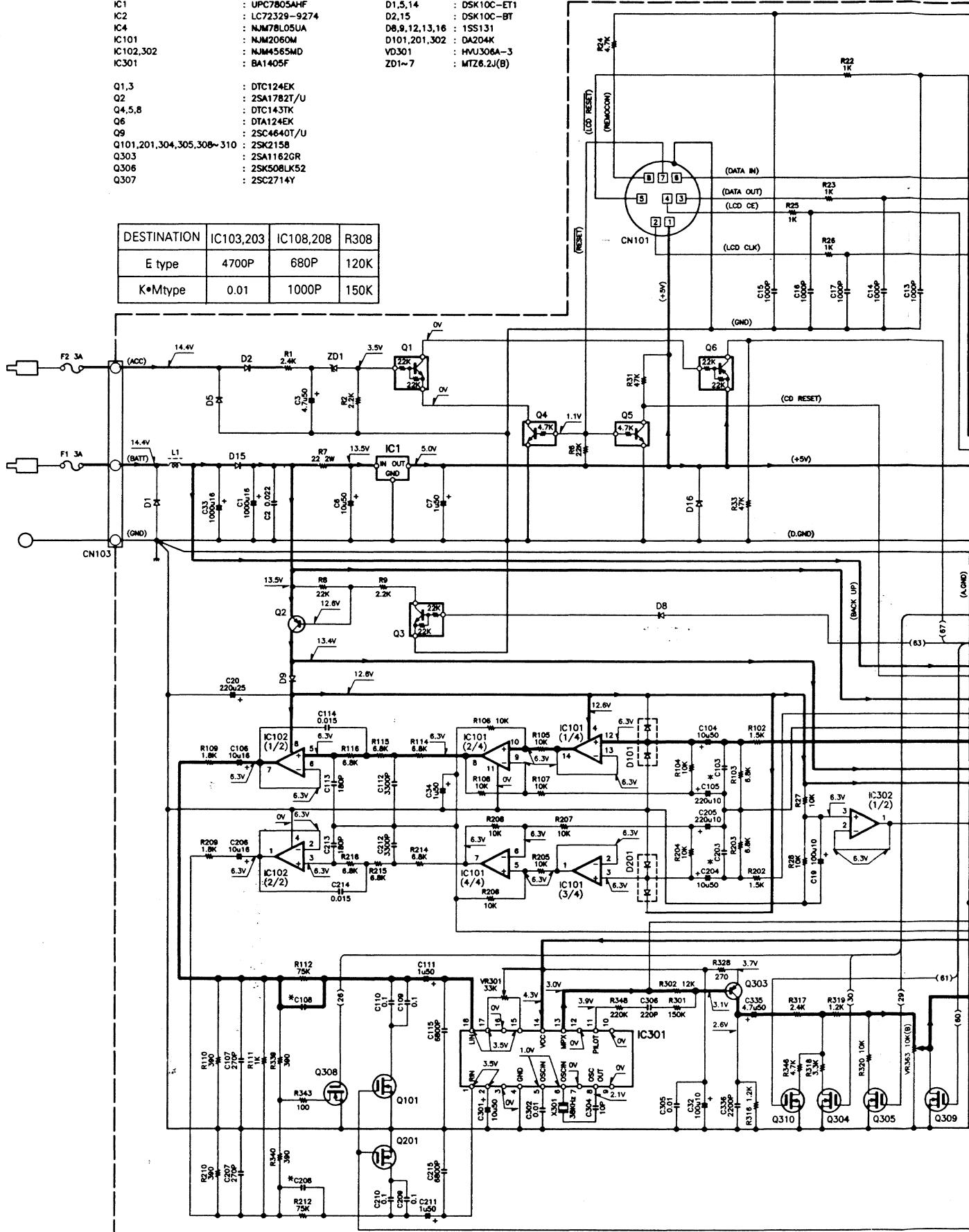


IC1 : UPC7805AHF
 IC2 : LC72329-9274
 IC4 : NJM7805UA
 IC101 : NJM2060M
 IC102,302 : NJM4565MD
 IC301 : BA1405F
 D1,5,14 : DSK10C-ET1
 D2,15 : DSK10C-BT
 D6,9,12,13,16 : DSS131
 D101,201,302 : DA204K
 VD301 : HVUJ306A-3
 ZD1~7 : MTZ6.2J(B)

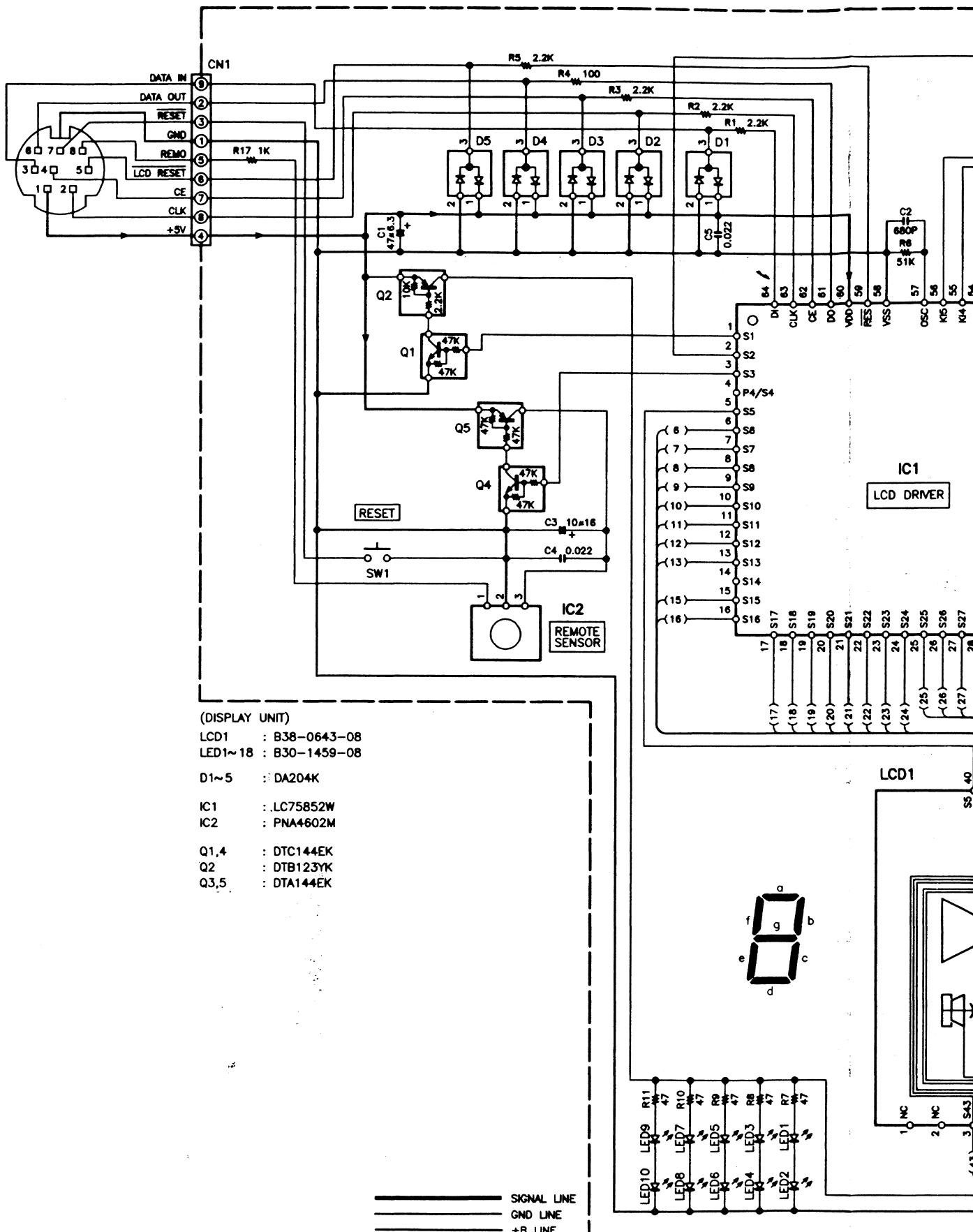
Q1,3 : DTC124EK
 Q2 : 2SA1782T/U
 Q4,5,8 : DTC143TK
 Q6 : DTA124EK
 Q9 : 2SC4640T/U
 Q101,201,304,305,308~310 : 2SK2158
 Q303 : 2SA1162GR
 Q306 : 2SK508LKS2
 Q307 : 2SC2714Y

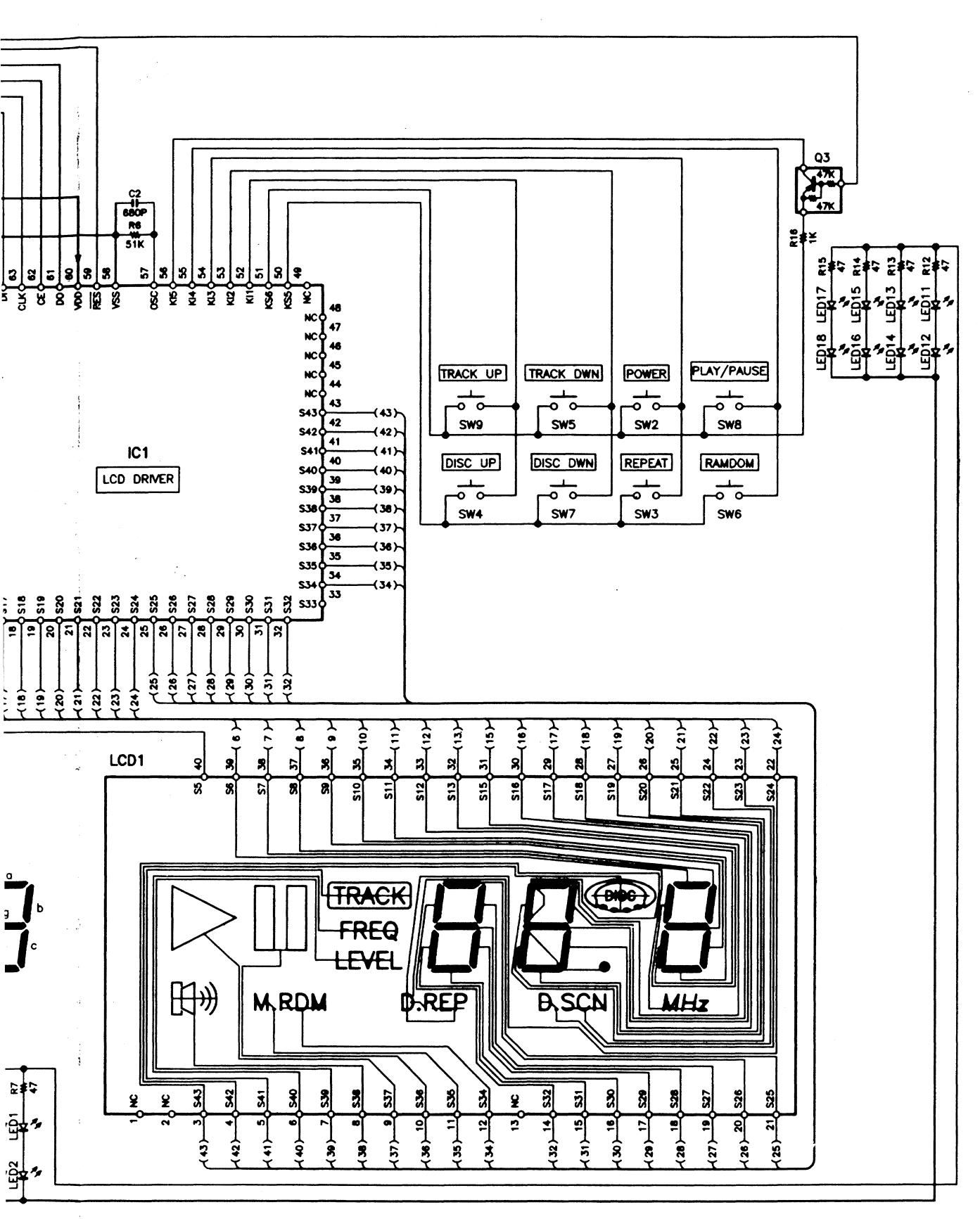
| DESTINATION | IC103,203 | IC108,208 | R308 |
|-------------|-----------|-----------|------|
| E type | 4700P | 680P | 120K |
| K•Mtype | 0.01 | 1000P | 150K |

RF MODULATOR UNIT



DISPLAY UNIT





KDC-C510FM

KENWOOD